

A syntax for cubical type theory

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Agda Ideas' Meeting XIX
May 23, 2014

Problem

- ▶ Goal: a type theory with the property:
if two objects are indistinguishable by observation, they are equal
- ▶ A candidate: homotopy type theory
 - ▶ Equality is defined by an inductive type with the J eliminator
 - ▶ Addition of the univalence axiom (“isomorphic types are equal”)
 - ▶ We don’t know how to run programs involving this axiom

Plan

- ▶ Homotopy type theory teaches us that equality can be described individually for each type former, eg.:

pairs:	$((a, b) =_{A \times B} (a', b'))$	\simeq	$(a =_A a' \times b =_B b')$
functions:	$(f =_{A \rightarrow B} g)$	\simeq	$(\Pi(x : A). f x =_B g x)$
natural numbers:	$(\text{zero} =_{\mathbb{N}} \text{zero})$	\simeq	1
	$(\text{zero} =_{\mathbb{N}} \text{suc } m)$	\simeq	0
	$(\text{suc } m =_{\mathbb{N}} \text{zero})$	\simeq	0
	$(\text{suc } m =_{\mathbb{N}} \text{suc } n)$	\simeq	$(m =_{\mathbb{N}} n)$

- ▶ Let's define equality separately for each type former, as above!

Inspiration and structure of talk

This work is based on the following papers:

- ▶ Bernardy, Moulin: A computational interpretation of parametricity, 2012
- ▶ Bezem, Coquand, Huber: A cubical set model of type theory, 2013

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Internal parametricity

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Kan Cubical sets

Basic setup

- ▶ Type theory with explicit substitutions, without the identity type
- ▶ Judgement types:

 $\vdash \Gamma$
 $\Gamma \vdash u : A$
 $\rho : \Gamma \Rightarrow \Delta$
 $\Gamma \vdash u \equiv v : A$
 $\rho \equiv \delta : \Gamma \Rightarrow \Delta$

- ▶ Applying substitutions:

$$\frac{\Gamma \vdash a : A \quad \rho : \Delta \Rightarrow \Gamma}{\Delta \vdash a[\rho] : A[\rho]}$$

$$\frac{\Gamma \vdash A : U \quad \rho : \Delta \Rightarrow \Gamma \quad \Delta \vdash t : A[\rho]}{(\rho, x \mapsto t) : \Delta \Rightarrow \Gamma, x : A}$$

Heterogeneous equality (i)

- ▶ For elements of a Σ -type, the second equality depends on the first:

$$((a, b) =_{\Sigma(x:A).B \times} (a', b')) \simeq (\Sigma(r : a =_A a').\text{transport}_B r b =_B a' b')$$

- ▶ To model this, we will a heterogeneous equality: a binary logical relation.

Heterogeneous equality (ii)

- ▶ The heterogeneous equality relation:

$$\frac{\Gamma \vdash A : U}{\Gamma^= \vdash \sim_A : A[0_\Gamma] \rightarrow A[1_\Gamma] \rightarrow U}$$

- ▶ $\Gamma^=$ is the context containing two copies of the context Γ and proofs that they are related.

$$\emptyset^= \equiv \emptyset$$

$$(\Gamma, x : A)^= \equiv \Gamma^=, x_0 : A[0_\Gamma], x_1 : A[1_\Gamma], \bar{x} : x_0 \sim_A x_1$$

- ▶ 0, 1 project out the corresponding components.

$$i_\emptyset \equiv () : \emptyset \Rightarrow \emptyset$$

$$i_{\Gamma, A} \equiv (i_\Gamma, x \mapsto x_i) : (\Gamma, x : A)^= \Rightarrow \Gamma, x : A$$

\sim on different type formers

Given $\Gamma \vdash A$, $\Gamma, x : A \vdash B$, we previously had:

$$\frac{\Gamma \vdash (a, b) : \Sigma(x : A).B \quad \Gamma \vdash (a', b') : \Sigma(x : A).B}{\Gamma \vdash ((a, b) =_{\Sigma(x : A).B} (a', b')) \simeq (\Sigma(r : a =_A a').\text{transport}_{\lambda x. B[x]} r b =_{B[a']} b')}$$

Now we have:

$$\frac{\Gamma.A \vdash B : U \quad \Gamma^= \vdash (a, b) : (\Sigma A B)[0] \quad \Gamma^= \vdash (a', b') : (\Sigma A B)[1]}{\Gamma^= \vdash (a, b) \sim_{\Sigma(x : A).B} (a', b') \equiv \Sigma(r : a \sim_A a'). \\ b \sim_B [x_0 \mapsto a, x_1 \mapsto a', \bar{x} \mapsto r] \quad b' : U}$$

For Π types:

$$\frac{\Gamma.A \vdash B : U \quad \Gamma^= \vdash f_0 : (\Pi A B)[0] \quad \Gamma^= \vdash f_1 : (\Pi A B)[1]}{\Gamma^= \vdash f_0 \sim_{\Pi A B} f_1 \equiv \Pi(x_0 : A[0], x_1 : A[1], \bar{x} : x_0 \sim_A x_1).f_0 x_0 \sim_B f_1 x_1 : U}$$

For the universe (we will replace this later):

$$A \sim_U B \equiv A \rightarrow B \rightarrow U$$

Every term is a congruence

We validate the rule

$$\frac{\Gamma \vdash u : A}{\Gamma^= \vdash u^\sim : u[0_\Gamma] \sim_A u[1_\Gamma]}$$

for each term former. This corresponds to showing that every term is parametric, eg.:

$$\frac{\Gamma . x : A \vdash b : B}{\Gamma^= \vdash (\lambda x.b)^\sim \equiv \lambda x_0, x_1, \bar{x}. b^\sim} \quad \frac{\Gamma \vdash f : \prod A B \quad \Gamma \vdash u : A}{\Gamma^= \vdash (f u)^\sim \equiv f^\sim u[0] u[1] u^\sim}$$

For types, we choose:

$$\frac{\Gamma \vdash A : U}{\Gamma^= \vdash A^\sim \equiv \sim_A}$$

Homogeneous equality

To internalise the logical relation, i.e. to have an equality in the same context, we define the substitution R and the term refl mutually:

$$\frac{\vdash \Gamma}{R_\Gamma : \Gamma \Rightarrow \Gamma^=} \quad \frac{\Gamma \vdash a : A}{\Gamma \vdash \text{refl } a \equiv (a^\sim)[R_\Gamma] : a \sim_A [R_\Gamma] a}$$

$$\emptyset \vdash R_\emptyset \equiv () : \emptyset$$

$$\Gamma.x : A \vdash R_{\Gamma.A} \equiv (R_\Gamma, x, x, \text{refl } x) : (\Gamma.A)^=$$

We introduce the abbreviation:

$$a =_A b \equiv a \sim_A [R] b$$

We also need an $S_\Gamma : (\Gamma^=)^= \Rightarrow (\Gamma^=)^=$, with a family of similar operations to refl .

The functor $-^=$ (i)

We can extend $-^=$ to act not only on contexts, but also terms, and substitutions:

$$\begin{array}{ll} \Gamma & \mapsto \Gamma^= \\ \Gamma \vdash t : A & \mapsto \Gamma^= \vdash t^= \equiv (t[0], t[1], t^\sim) : A^= \\ (\rho, x \mapsto t) & \mapsto (\rho^=, t^=) \end{array}$$

Higher dimensions (i)

By iterating \equiv , we get higher dimensional cubes:

Γ	$\vdash x : A$			
$\Gamma^=$	$\vdash (x : A)^1 \equiv$	$x_0 : A[0_\Gamma].x_1 : A[1_\Gamma].\bar{x} : x_0 \sim_A x_1$		
Γ^2	$\vdash (x : A)^2 \equiv$	$x_{00} : A[0_\Gamma 0_\Gamma =]$	$x_{01} : A[0_\Gamma 1_\Gamma =]$	$\bar{x}_0 : x_{00} \sim_{A[0_\Gamma]} x_{01}$
		$.x_{10} : A[1_\Gamma 0_\Gamma = .A[0]]$	$.x_{11} : A[1_\Gamma 1_\Gamma = .A[0]]$	$.x_1 : x_{10} \sim_{A[1_\Gamma]} x_{11}$
		$.(\bar{x})_0 : (x_0 \sim_A x_1)[0_\Gamma = .A[0].A[1]].(\bar{x})_1 : (x_0 \sim_A x_1)[1_\Gamma = .A[0].A[1]].\bar{\bar{x}} : (\bar{x})_0 \sim_{x_0 \sim_A x_1} (\bar{x})_1$		
Γ^3	$\vdash (x : A)^3 \equiv$	$x_{000} : A[000]$	$x_{001} : A[001]$	$\bar{x}_{00} : x_{000} \sim_{A[00]} x_{001}$
		$.x_{010} : A[010]$	$.x_{011} : A[011]$	$.x_{01} : x_{010} \sim_{A[01]} x_{011}$
		$.(\bar{x})_0 : x_{000} \sim_{A[0]} [0] x_{010}$	$.(\bar{x})_1 : x_{001} \sim_{A[0]} [1] x_{011}$	$.x_{\bar{0}} : (\bar{x})_0 \sim_{x_{00} \sim_{A[0]} x_{01}} (\bar{x})_1$
		$.x_{100} : A[100]$	$.x_{101} : A[101]$	$.x_{\bar{1}} : x_{100} \sim_{A[10]} x_{101}$
		$.x_{110} : A[110]$	$.x_{111} : A[111]$	$.x_{\bar{11}} : x_{110} \sim_{A[11]} x_{111}$
		$.(\bar{x})_0 : x_{100} \sim_{A[1]} [0] x_{110}$	$.(\bar{x})_1 : x_{101} \sim_{A[1]} [1] x_{111}$	$.x_{\bar{1}} : (\bar{x})_0 \sim_{x_{10} \sim_{A[1]} x_{11}} (\bar{x})_1$
		$.(\bar{x})_{00} : x_{000} \sim_A [00] x_{100}$	$.(\bar{x})_{01} : x_{001} \sim_A [01] x_{101}$	$.(\bar{x})_{00} : (\bar{x})_{00} \sim_{x_{00} \sim_{A[0]} x_{10}} (\bar{x})_{01}$
		$.(\bar{x})_{10} : x_{010} \sim_A [10] x_{110}$	$.(\bar{x})_{11} : x_{011} \sim_A [11] x_{111}$	$.(\bar{x})_{10} : (\bar{x})_{10} \sim_{x_{01} \sim_{A[1]} x_{11}} (\bar{x})_{11}$
		$.(\bar{x})_0 : (\bar{x})_{00} \sim_{x_0 \sim_A x_1} [0] (\bar{x})_{10}.(\bar{x})_1 : (\bar{x})_{01} \sim_{x_0 \sim_A x_1} [1] (\bar{x})_{11}.\bar{\bar{x}} : (\bar{x})_0 \sim_{(\bar{x})_0 \sim_{x_0 \sim_A x_1} (\bar{x})_1} (\bar{x})_1$		

Higher dimensions (ii)

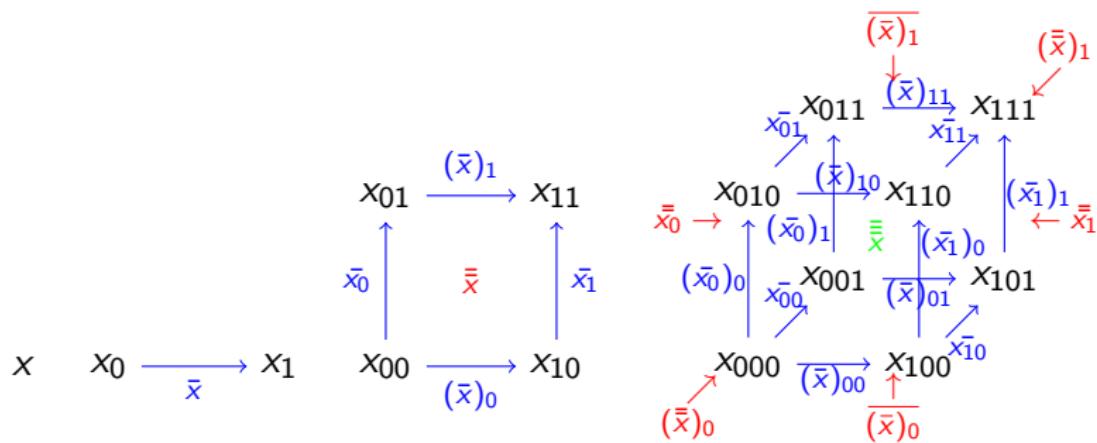


Figure: Cubes of dimension 0-3.

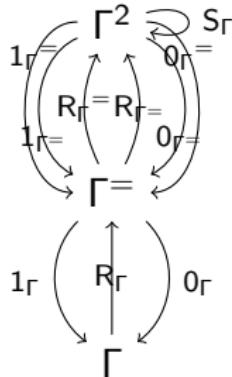
The functor $_{}^=$ (ii)

The iterated version of $_{}^=$ makes any context into a presheaf over the base category of cubical sets.

So, a context Γ is a presheaf $\mathcal{C} \rightarrow \text{Con}$ where

- ▶ \mathcal{C} is the category of names and substitutions for the cubical set model,
- ▶ Con is the category of contexts and substitutions in the term model.

...



Definition of \sim_U

Our previous definition:

$$A \sim_U B \equiv A \rightarrow B \rightarrow U$$

We replace this by:

$$\Gamma \vdash A \sim_U B \equiv \Sigma -\sim- : A \rightarrow B \rightarrow U$$

$$\text{coe}^0 : A \rightarrow B$$

$$\text{coh}^0 : \Pi(x : A).x \sim \text{coe}^0 x$$

$$\text{uni}^0 : \Pi(x : A, p p' : \Sigma(y : B).x \sim y).p = p'$$

$$\text{coe}^1 : B \rightarrow A$$

$$\text{coh}^1 : \Pi(y : B).\text{coe}^1 y \sim y$$

$$\text{uni}^1 : \Pi(y : B, p p' : \Sigma(x : A).x \sim y).p = p'$$

Kan conditions (i)

We are required to provide coe and coh now for each type former.
 For Σ we can define it as

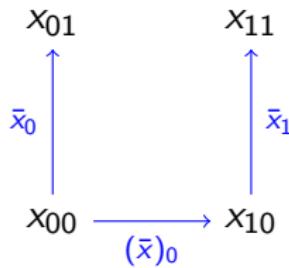
$$\begin{aligned} \Gamma^= \vdash \text{coe}_{\Sigma(x:A).B}^i &\equiv \lambda(a, b).(\text{coe}_A^i a, \text{coe}_B^i[\bar{x} \mapsto \text{coh}_i^1 a] b) \\ &: (\Sigma(x : A).B)[i] \rightarrow (\Sigma(x : A).B)[1 - i] \end{aligned}$$

$$\begin{aligned} \Gamma^= \vdash \text{coh}_{\Sigma(x:A).B}^i &\equiv \lambda(a, b).(\text{coh}_A^i a, \text{coh}_B^i[\bar{x} \mapsto \text{coh}_i^1 a] b) \\ &: \prod(w : (\Sigma(x : A).B)[i]) . w \stackrel{i}{\sim}_{\Sigma(x:A).B} \text{coe}_i^1 w \end{aligned}$$

Kan conditions (ii)

coe and coh can be seen as first level Kan operations: given a point, they extend it to a line.

A higher level Kan operation completes an incomplete square, 3-dimensional cube, etc. Eg.:



To define the first level Kan operations for Π , we need the second level Kan operations. However,

$$\Gamma^= .x_0 : A[0].x_1 : A[1] \vdash x_0 \sim_A x_1 : U,$$

so

$$(\Gamma^= .x_0 : A[0].x_1 : A[1])^= \vdash (x_0 \sim_A x_1)^\sim : (x_{00} \sim_A [0] x_{10}) \sim_U (x_{01} \sim_A [1] x_{11}).$$

Kan for Π

Coerce for Π :

$$\begin{aligned} \Gamma^= \vdash \text{coe}_{\Pi(x:A).B}^0 &\equiv \lambda f. \lambda x. \text{coe}_B^0[\bar{x} \mapsto \text{coh}_A^1 x] (f(\text{coe}_A^1 x)) \\ &: (\Pi(x : A[0]).B[0, x]) \rightarrow (\Pi(x : A[1]).B[1, x]) \end{aligned}$$

The type of the coherence operation:

$$\Gamma^= \vdash \text{coh}_{\Pi(x:A).B}^0 : \Pi(f : (\Pi(x : A).B)[0]. f \sim_{\Pi(x:A).B} (\text{coe}_{\Pi(x:A).B}^0 f))$$

We get coherence by using higher level Kan:

$$\begin{array}{ccc} \begin{array}{c} x_1 \\ \xrightarrow{\text{refl } x_1} \\ x_1 \end{array} & \begin{array}{c} \text{coh}_B^0[\bar{x} \mapsto \text{coh}_A^1 x_1] (f(\text{coe}_A^1 x_1)) \\ f(\text{coe}_A^1 x_1) \xrightarrow{\quad} \text{coe}_B^0[\bar{x} \mapsto \text{coh}_A^1 x_1] (f(\text{coe}_A^1 x_1)) \\ f \sim [\text{R}_{\Gamma^=}] x_0 | (\text{coe}_A^1 x_1) r \\ \uparrow \\ f x_0 \xrightarrow{\quad} \text{co}e_B^0[\bar{x} \mapsto \text{coh}_A^1 x_1] (f(\text{coe}_A^1 x_1)) \\ \text{coh}_{\Pi(x:A).B}^0 f x_0 x_1 \bar{x} \end{array} & \begin{array}{c} \text{refl } (\text{co}e_B^0[\bar{x} \mapsto \text{coh}_A^1 x_1] (f(\text{coe}_A^1 x_1))) \\ \uparrow \\ \text{co}e_B^0[\bar{x} \mapsto \text{coh}_A^1 x_1] (f(\text{coe}_A^1 x_1)) \end{array} \\ \begin{array}{c} x_1 \\ \uparrow \\ \bar{x} \\ \uparrow \\ x_0 \\ \xrightarrow[r]{\quad} \text{co}e_A^1 x_1 \end{array} & \begin{array}{c} \text{coh}_A^1 x_1 \\ \uparrow \\ \text{co}e_A^1 x_1 \end{array} & \end{array}$$

Identity type (i)

Non-dependent eliminator:

$$\frac{\Gamma \vdash P : A \rightarrow U \quad \Gamma \vdash r : x \sim_A [R_\Gamma] y \quad \Gamma \vdash u : Px}{\Gamma \vdash \text{transport}_P r u : Py}$$

We have that P is a congruence:

$$\frac{\Gamma \vdash P : A \rightarrow U}{\Gamma \vdash P^\sim[R_\Gamma] : \prod(x_0, x_1 : A, \bar{x} : x_0 \sim_A [R_\Gamma] x_1). Px_0 \sim_U Px_1}$$

And we define transport by using $P^\sim[R]$:

$$\frac{\Gamma \vdash P : A \rightarrow U \quad \Gamma \vdash r : x =_A y \quad \Gamma \vdash u : Px}{\Gamma \vdash \text{transport}_P r u \equiv (P^\sim[R_\Gamma] x y r).\text{coe}^0 u : Py}$$

Identity type (ii)

The computation rule of transport says that $\text{transport}_P(\text{refl } x) \equiv \text{id}$. We have

$$\begin{aligned}
 & \text{transport}_P(\text{refl } x) \\
 & \equiv (P^\sim[R_\Gamma] x x x^\sim[R_\Gamma]).\text{coe}^0 \\
 & \equiv (P x)^\sim[R_\Gamma].\text{coe}^0 \\
 & \equiv \text{id}
 \end{aligned}$$

The last step is justified by adding the following rule:

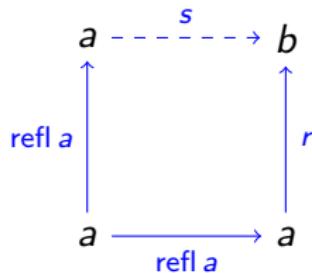
$$\frac{\Gamma \vdash A : U}{\Gamma \vdash A^\sim[R_\Gamma] \equiv (-\sim_A[R_\Gamma] -, \text{id}, \text{refl}, \text{id}, \text{refl}) : A \sim_U A}$$

Identity type (iii)

We also show that singletons are contractible i.e. we show how to construct the terms s and t of the following type:

$$\frac{\Gamma \vdash a, b : A \quad \Gamma \vdash r : a =_A b}{\begin{aligned} \Gamma \vdash (s, t) : & (a, \text{refl } a) =_{\Sigma(x:A).a=_Ax} (b, r) \\ \equiv & \Sigma(s : a \sim_A [R_\Gamma] b). \text{refl } a \sim_{a \sim_A [R_\Gamma] x} [R_\Gamma, a, b, s] r \end{aligned}}$$

s is constructed by filling the following incomplete square from bottom to top:



Conclusion

- ▶ A different presentation of Bernardy and Moulin's work on internal parametricity: equality defined as a logical relation.
- ▶ Using equivalence for elements of the universe instead of any relation.
- ▶ This forces us to define the first level Kan operations for type formers.
- ▶ Higher Kan operations can be computed from the first level Kan operations.
- ▶ Unfinished work:
 - ▶ Relation to the uniformity condition in the Bezem, Coquand, Huber cubical set model
 - ▶ Prove decidability, canonicity
 - ▶ Examples of higher inductive types
 - ▶ Implement it in Agda
 - ▶ Create a proof assistant based on this theory :)